A method of computing a distance measure between first and second mixture type 1. probability distribution functions,

$$G(x) = \sum_{i=1}^{N} \mu_i g_i(x), \qquad H(x) = \sum_{k=1}^{K} \gamma_k h_k(x),$$

$$H(x) = \sum_{k=1}^{K} \gamma_k h_k(x),$$

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comprising the step of evaluating the equation:

$$D_{M}(G, H) = \min_{w = [\omega_{ik}]} \sum_{i=1}^{N} \sum_{k=1}^{K} \omega_{ik} d(g_{i}, h_{k}),$$

where $d(g_i, h_k)$ is a function of the distance between a component, g_i , of the first probability distribution function and a component, hk, of the second probability distribution function

where

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$$\sum_{i=1}^{N} \mu_i = 1 \quad and \quad \sum_{k=1}^{K} \gamma_k = 1.$$

$$\omega_{ik} \ge 0$$
, $1 \le i \le N$, $1 \le k \le K$

$$\sum_{k=1}^{K} \omega_{ik} = \mu_i, \ 1 \le i \le N, \ \sum_{i=1}^{N} \omega_{ik} = \gamma_k, \ 1 \le k \le K.$$

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The method according to claim 1 wherein at least one of said first and second 2. mixture probability distribution functions includes a Gaussian Mixture Model.

- The method according to claim 1 wherein the element distance between the first and
 second probability distance functions includes Kullback Leibler Distance.
 - 4. The method of claim 1 wherein the first and second probability distribution functions are Gaussian mixture models derived from audio segments.
- 10 5. A computer program embedded in a storage medium for computing a distance measure between first and second mixture type probability distribution functions,

$$G(x) = \sum_{i=1}^{N} \mu_{i} g_{i}(x),$$
 $H(x) = \sum_{k=1}^{K} \gamma_{k} h_{k}(x),$

in accordance with the equation:

$$D_{M}(G, H) = \min_{w=[\omega_{k}]} \sum_{i=1}^{N} \sum_{k=1}^{K} \omega_{ik} d(g_{i}, h_{k}),$$

where $d(g_i, h_k)$ is a function of the distance between a component, g_i , of the first probability distribution function and a component, h_k , of the second probability distribution function

where

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$$\sum_{i=1}^{N} \mu_{i} = 1 \text{ and } \sum_{k=1}^{K} \gamma_{k} = 1.$$

and

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$$\omega_{ik} \geq 0, \ 1 \leq i \leq N, \ 1 \leq k \leq K$$

and
$$\sum_{k=1}^K \omega_{ik} = \mu_i, \ 1 \leq i \leq N, \ \sum_{i=1}^N \omega_{ik} = \gamma_k, \ 1 \leq k \leq K.$$

- 6. The computer program according to claim 5 wherein at least one of said first and second mixture probability distribution functions includes a Gaussian Mixture Model.
 - 7. The computer program according to claim 5 wherein the element distance between the first and second probability distance functions includes Kullback Leibler Distance.
- 10 8. The computer program of claim 5 wherein the first and second probability distribution functions are Gaussian mixture models derived from audio segments.
 - 9. A computer system for computing a distance measure between first and second mixture type probability distribution functions,

$$G(x) = \sum_{i=1}^{N} \mu_i g_i(x),$$
 $H(x) = \sum_{k=1}^{K} \gamma_k h_k(x),$

in accordance with the equation:

$$D_{M}(G,H) = \min_{w = [\omega_{k}]} \sum_{i=1}^{N} \sum_{k=1}^{K} \omega_{ik} d(g_{i},h_{k}),$$

where $d(g_i, h_k)$ is a function of the distance between a component, g_i , of the first probability distribution function and a component, h_k , of the second probability distribution function

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$$\sum_{i=1}^{N} \mu_{i} = 1 \text{ and } \sum_{k=1}^{K} \gamma_{k} = 1.$$

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$$\omega_{ik} \ge 0, \ 1 \le i \le N, 1 \le k \le K$$

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$$5 \qquad \sum_{k=1}^K \omega_{ik} = \mu_i, \, 1 \leq i \leq N, \, \sum_{i=1}^N \omega_{ik} = \gamma_k, \, 1 \leq k \leq K.$$

- 10. The computer system according to claim 9 wherein at least one of said first and second mixture probability distribution functions includes a Gaussian Mixture Model.
- 11. The computer system according to claim 9 wherein the element distance between the first and second probability distance functions includes Kullback Leibler Distance.
- 12. The computer system of claim 9 wherein the first and second probability distribution functions are Gaussian mixture models derived from audio segments.
 - 13. A method for computing a distance measure between first and second mixture type probability distribution functions G and H, wherein:

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$$G(x) = \sum_{i=1}^{N} \mu_{i} g_{i}(x),$$

wherein μ_i is a weight imposed on a component, $g_i(x)$, of the first probability distribution function and

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$$H(x) = \sum_{k=1}^{K} \gamma_k h_k(x),$$

wherein γ_k is a weight imposed on a component h_k , of the second probability distribution function comprising the steps of:

- computing an element distance, $d(g_i, h_k)$, between each g_i and each h_k where $1 \le i \le N, 1 \le k \le K$,
- computing an overall distance, denoted by $D_M(G,H)$, between the first mixture probability distribution function, G, and the second mixture probability distribution function, H, based on a weighted sum of the all element distances,

$$\sum_{i=1}^{N}\sum_{k=1}^{K}\omega_{ik}d(g_{i},h_{k}),$$

wherein weights $\omega_{i,k}$ imposed on the element distances $d(g_i, h_k)$, are chosen so that the overall distance $D_M(G, H)$ is minimized and

$$\omega_{ik} \ge 0, \quad 1 \le i \le N, 1 \le k \le K$$

$$\sum_{i=1}^{N} \omega_{ik} = \gamma_{k}, 1 \le k \le K, \quad and$$

$$\sum_{k=1}^K \omega_{ik} = \mu_i, 1 \le i \le N.$$

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- 14. The method according to claim 13 wherein at least one of said first and second mixture probability distribution functions includes a Gaussian Mixture Model.
- 20 15. The method according to claim 13 wherein the element distance between the first and second probability distance functions includes Kullback Leibler Distance.
 - 16. The method of claim 13 wherein the first and second probability distribution functions are Gaussian mixture models derived from audio segments.

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